

Share With Thy Neighbors: Single-View Reconstruction by Cross-Instance Consistency

Tom Monnier¹

Matthew Fisher^②

Alexei A. Efros³

Mathieu Aubry^①

https://www.tmonnier.com/UNICORN/

Overview and challenges

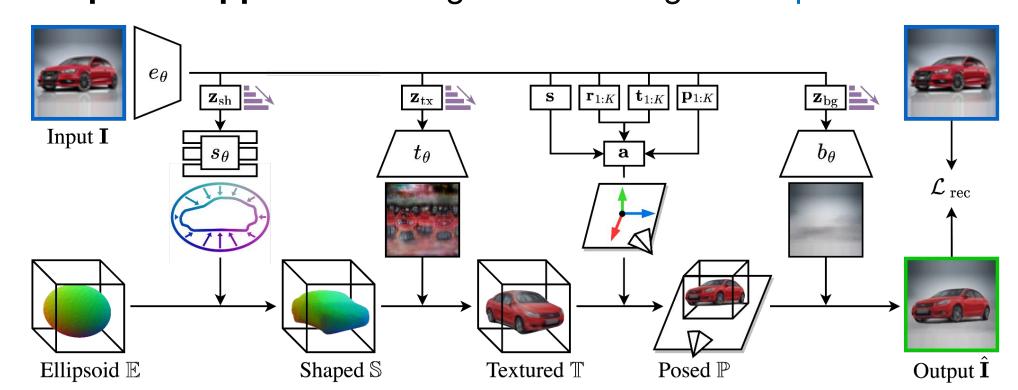
Goal → predict 3D from a single image without supervision

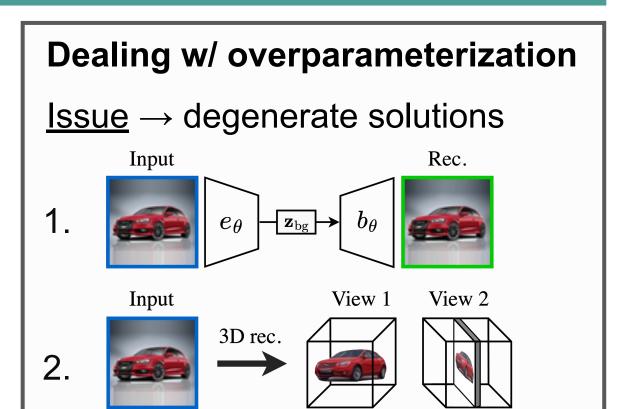
Previous works → supervision / priors limiting applicability

Method	Supervision	Data
SoftRas [1], DVR [2]	MV, CK, S	ShapeNet
CMR [3], SDF-SRN [4], TARS-3D [5]	CK, S	ShapeNet, Real
IMR [6], UMR [7], UCMR [8], SMR [9]	S, A	Real
Ours	None	ShapeNet, Real

Multi-View, Camera/Keypoints, Silhouette, Assumption (template, symmetry)

Proposed approach → img autoencoding into explicit factors

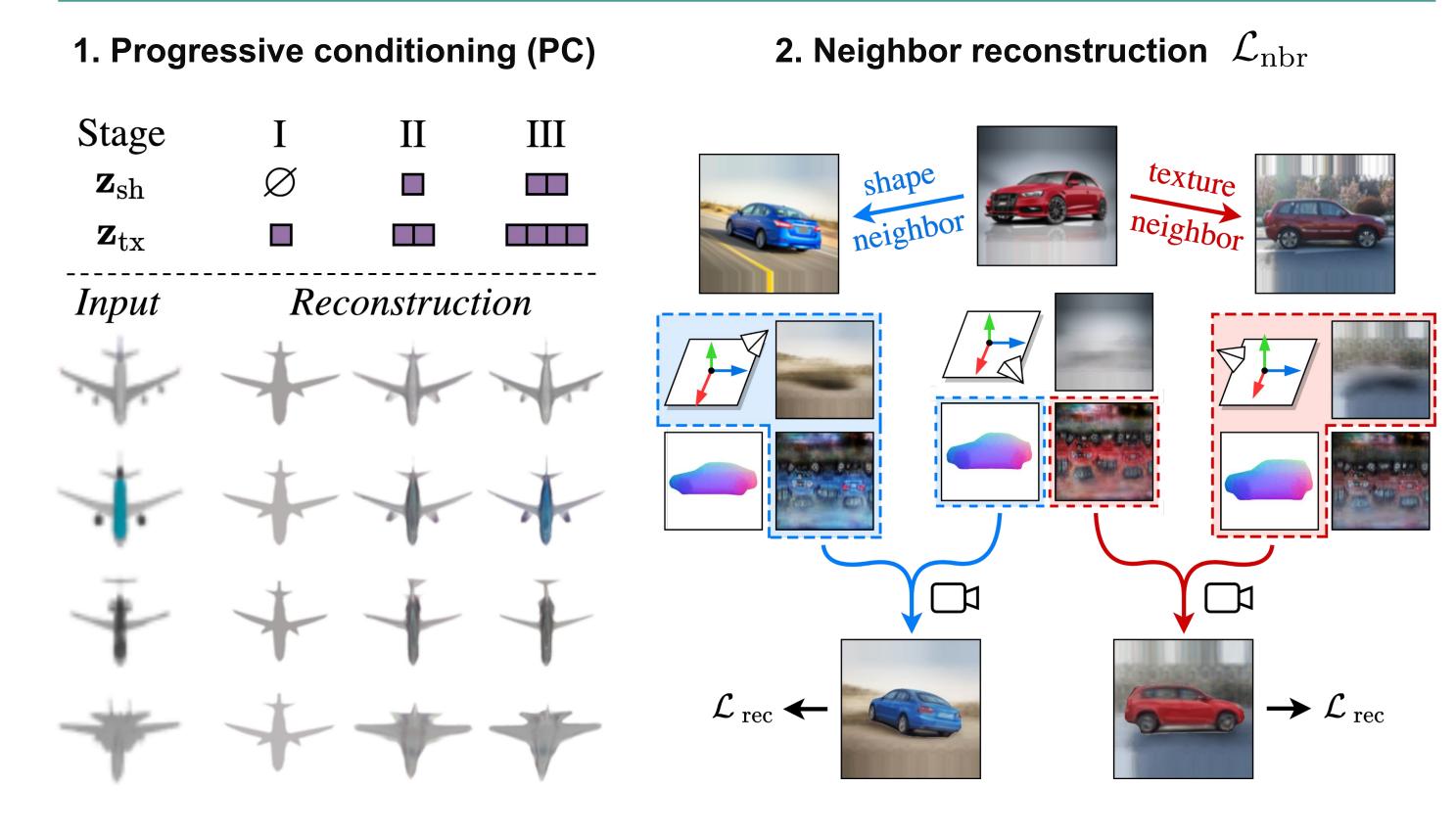




Cross-instance consistency (SSL)

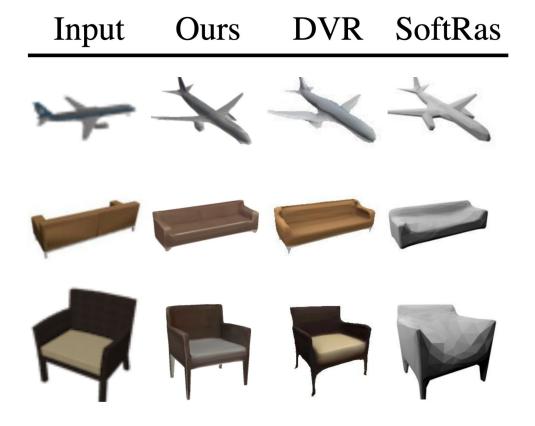
- 1. Progressive conditioning (PC) = curriculum learning procedure encouraging shared features
- 2. Neighbor reconstruction = training loss explicitly enforcing consistency between neighbors

UNICORN: UNsup. Instance COnsistency for 3D ReconstructioN



Results

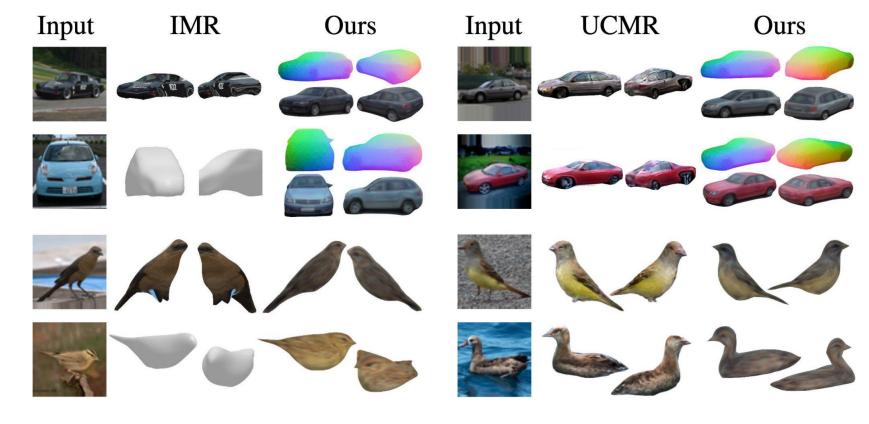
Comparison on ShapeNet [A]



Method	Ours	SDF-SRN	DVR	DVR
$rac{\mathbf{MV}}{\mathbf{CK}}$		\checkmark	\checkmark	√
S		√	√	√
airplane	0.110	0.128	0.114	0.111
$\overline{\operatorname{car}}$	0.168	0.150	0.203	0.153
chair	0.253	0.262	0.371	0.205
mean	0.177	0.180	0.229	0.156

- [A] ShapeNet, Chang et al., arXiv 2015
- [B] PASCAL, Xiang et al., WACV 2014
- [C] CUB-200, Welinder et al., Cal. Inst. of Tech. 2010
- [D] CompCars, Yang et al., CVPR 2015 [E] LSUN, Yu et al., arXiv 2016

Comparison on Pascal3D+ Car [B] & CUB [C]

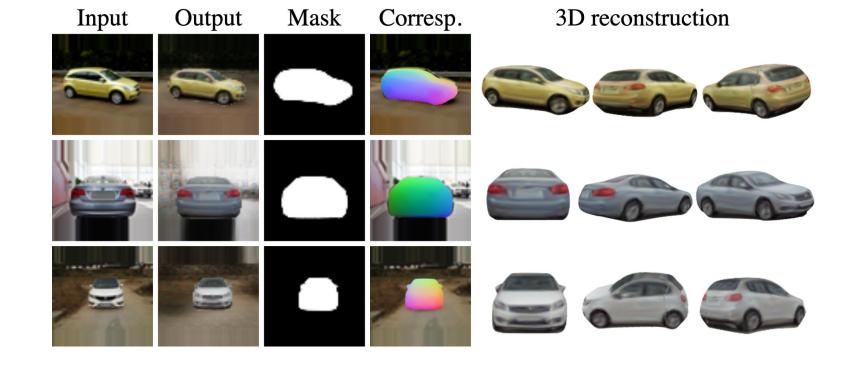


	Supe	rvis	ion	Pascal3D+ Car		CUB-200-2011		
Method	$\overline{\mathbf{C}\mathbf{K}}$	S	A	3D IoU↑	$\text{Ch-}L_1\downarrow$	Mask IoU↑	PCK@0.1↑	Mask IoU↑
$\overline{\mathrm{CMR}}$	\checkmark	\checkmark	\checkmark	64	_	-	48.3	70.6
IMR		\checkmark	\checkmark	_	-	-	53.5	_
UMR		\checkmark	\checkmark	62	_	-	58.2	73.4
UCMR		\checkmark	\checkmark	67.3	0.172	73.7	-	63.7
SMR		\checkmark	\checkmark	_	_	-	62.2	80.6
Ours				65.9	0.163	83.9	49.0	71.4

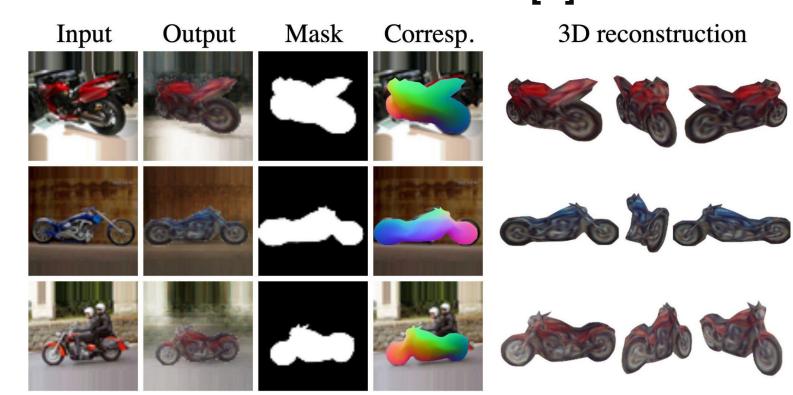
- [1] Soft Rasterizer, Liu et al., ICCV 2019
- [2] DVR, Niemeyer et al., CVPR 2020
- [3] CMR, Kanazawa et al., ECCV 2018
- [4] SDF-SRN, Lin et al., NeurlPS 2020[5] TARS-3D, Duggal and Pathak, CVPR 2022

[6] IMR, Tulsiani et al., arXiv 2020 [7] UMR, Li et al., ECCV 2020 [8] UCMR, Goel et al., ECCV 2020 [9] SMR, Hu et al., CVPR 2021

Other real images - CompCars [D]



LSUN Motorbike [E]



Ablation study

Qualitative study on SN [A] & CompCars [D]

Input	Full model	w/o $\mathcal{L}_{ m nbr}$	w/o PC	

Quantitative analysis on ShapeNet [A]

Model	Full	$rac{ m w/o}{{\cal L}_{ m nbr}}$	w/o PC
airplane bench car chair table	0.110 0.159 0.168 0.253 0.243	$\begin{array}{c} 0.124 \\ 0.188 \\ 0.179 \\ 0.319 \\ 0.246 \end{array}$	0.107 0.206 0.173 0.527 0.598
mean	0.187	0.211	0.322

PyTorch code & video results

